

### a.) Substitute Specification

## METHOD AND APPARATUS FOR LOW-SPEED, HIGH-THROUGHPUT FIBER DRAWING USING COILED FIBER LOOPS

### BACKGROUND OF THE INVENTION

This invention relates to a method and apparatus for drawing fibers, yarns, or relatively narrow tapes formed from natural resin, synthetic resin, or combination of both. In the description of this invention, which follows, for the sake of convenience, the method and apparatus will be described in terms of drawing fibers. However, it is to be understood that the method and apparatus are equally usable for drawing any elongated body elements subject to such procedure. The invented drawing method and apparatus will be described in terms of drawing of fibers in the form of coiled fiber loops. It is to be understood that the coiled fiber loops are a connected set of rings or twists into which the fiber can be wound.

In the production of most polymer fibers (e.g., nylon, polypropylene, and polyester fibers) a drawing stage is included subsequent to the spinning or extrusion stage. In the drawing stage the fiber is usually drawn by a drawing apparatus at elevated temperature to a length substantially exceeding (in some cases, several times) their original length. The fiber passes the drawing apparatus with a speed  $V_{fiber}$  which increases from the beginning to the end of the drawing stage, speed  $V_{fiber}$  being a linear speed along the fiber axis of fiber points in the drawing process (along the tangent to the fiber axis if the fiber drawing occurs on the curved surface, e.g., a curved hot plate or a roller). A fiber draw ratio  $\lambda$ , which is the extent of fiber drawing, is given by

$$\lambda = V_{fiber2}/V_{fiber1}, \quad (1)$$

where  $V_{fiber1}$  is fiber speed  $V_{fiber}$  in the beginning of the fiber drawing stage, and  $V_{fiber2}$  is fiber speed  $V_{fiber}$  at the end of the fiber drawing stage.

The drawing of the fibers enables them to achieve the required molecular orientation and structure by virtue of which they attain the necessary strength and other desired physical characteristics. As an example, typical  $\lambda$  for commercial nylon fibers is about 6 to 1. Usually, the higher  $\lambda$ , the higher molecular orientation and fiber tensile properties (tenacity and Young modulus in particular).

In the case of a continuous multi-stage drawing process,  $V_{fiber2}$  is the fiber linear speed at the end of the last fiber drawing stage, and  $V_{fiber1}$  is the fiber linear speed in the beginning of the first fiber drawing stage.

The drawing has generally been hitherto effected on a commercial scale by passing the fiber from one set of rotating rollers to another. Each set of the receiving rollers rotates at a surface speed, which is greater than that of the preceding set of feed rollers.

In the case of drawing the fiber by the rotating rollers we get

$$V_{fiber1} = V_{surface1} = V_{inlet} \quad \text{and} \quad (2)$$

$$V_{fiber2} = V_{surface2} = V_{outlet}, \quad (3)$$

where  $V_{surface1}$  is a linear surface speed of the feed rollers,

$V_{surface2}$  is a linear surface speed of the receiving rollers,

$V_{inlet}$  is a fiber inlet speed, which is a fiber linear speed along the fiber axis of feeding the fiber to the feed rollers, and

$V_{outlet}$  is a fiber outlet speed, which is a fiber linear speed along the fiber axis of conveying the drawn fiber from the drawing stage either to a next stage of the continuous fiber making process (drawing, heat setting, relaxation, bulking or texturing, twisting, finish application, etc.) or to a receiving package.

Thus in conventional industrial drawing processes a ratio of fiber outlet speed  $V_{outlet}$  to fiber speed  $V_{fiber2}$  is 1 to 1 (this ratio will be used for discussion below).

In the case of conveying drawn fiber after the drawing stage to the receiving package we get

$$V_{fiber2} = V_{outlet} = V_{take-up}, \quad (4)$$

where  $V_{take-up}$  is a take-up speed, which is a fiber linear speed along the fiber axis of taking up the drawn fiber on the receiving package (in some cases,  $V_{take-up}$  is slightly higher than  $V_{fiber2}$  and  $V_{outlet}$  to provide some tension in the taken-up fiber).

Outlet speed  $V_{outlet}$  and take-up speed  $V_{take-up}$  determine the throughput of the drawing stage. Most conventional commercial processes, particularly in the area of melt-spun aliphatic flexible-chain polymer fibers, have very high speed  $V_{take-up}$  ranging from several hundred to several thousand meters per minute to provide high throughput. This means that in these the high-throughput commercial processes speeds  $V_{fiber2}$ , and  $V_{outlet}$  are also high, i.e., ranging from several hundred to several thousands meters per minute.

Another parameter is used to characterize the fiber drawing process, i.e., a speed of drawing or a strain rate  $V_{strain}$ , which is a relative deformation of the fiber (strain) in a unit time. Usually strain rate  $V_{strain}$  is expressed in percent per second (%/sec) and is given by

$$V_{strain} = \lambda/T, \quad (5)$$

where  $T$  is time of drawing.

In conventional commercial processes strain rate  $V_{strain}$  is high, i.e., several hundred percent per second.

In such conventional high-fiber-speed, high-drawing-speed processes the fiber is subjected to a very abrupt acceleration and rise in tension at the point where it leaves one roller to pass to the

succeeding higher-speed roller. Care must be taken to ensure that the abrupt rise in tension does not break the fiber. Thus, this conventional technique may be termed “impulsive drawing” because the fiber experiences a sudden “impulsive” acceleration from its initial state to its final drawn state while traveling through the drawing machine. The “impulsive” acceleration and high tension result in frequent fiber breaks and equipment stops, high volume of waste, and prevent further fiber improvement.

Because of high fiber speed, time of drawing T is very short in most high-throughput industrial processes, i.e., less than a second for one-stage one-stage drawing and about 1-3 seconds for ~~two- or three-stage~~ two- or three-stage drawing. This results in non-equilibrium drawing where the fiber does not have enough time to be heated to ambient elevated temperature while being drawn, and the drawing occurs at high temperature gradient in the fiber cross-section. This, in turn, results in reduced drawability, reduced crystallinity, high gradient of morphology and physical properties in the cross-section, high local overstresses, and dimensionally unstable fibers with high ~~hot-air~~ hot-air shrinkage. This is especially typical for fibers and yarns having high denier (denier is weight in grams of 9000 meters of fiber). To provide additional time for heat setting, the existing technology requires a separate, specialized, very expensive, and energy-consuming equipment to produce dimensionally stable fibers without decrease of their tensile properties (U.S. Pat. No. 5,522,161 to Vetter (1996), U.S. Pat. No. 5,588,604 to Vetter et al. (1996) – these patents are discussed below). More often, a different method for decreasing shrinkage is used in commercial processes. The fiber is subjected to restricted shrinkage while moving through a special stage, which follows the last drawing stage. In doing so, the initial modulus, intermediate moduli, and tenacity are reduced.

The commercial drawing processes mentioned above do not enable one to produce polymer fibers with tensile and other physical properties close to those made by lab-scale low-fiber-speed, low-drawing-speed, long-drawing-time, and non-impulsive drawing process. This lab-scale drawing may be termed “uniform” or “equilibrium” drawing, where drawing time T is long enough to heat the fiber to the ambient temperature, while it being drawn, with low temperature gradient in the fiber cross-section. This results in uniform morphology and physical properties in the cross-section. These lab-scale experiments achieve more effective morphological transition “low-oriented -- high-oriented polymer system” and superior physical properties. For example, tenacity

of lab-scale aliphatic flexible-chain, regular-molecular-weight, melt-spun polymer samples is higher by a factor of about 1.5-2 and initial moduli are several times higher than those for conventional commercial fibers. (As an example, tensile properties of lab-scale polypropylene fibers can be seen in "Superdrawn Filaments of Polypropylene" by W. N. Taylor, JR. and E. S. Clark, Polym. Eng. Sci., 18, 518-526 (1978). A comparison of these results with tensile properties of commercial polypropylene fibers is presented in Table V below). In order to overcome this large gap between the properties of lab-scale and commercial-scale polymer fibers, a new approach needs to be developed.

Moreover, within today fiber industry there is another large gap, i.e., tensile properties of low-cost, low-performance, regular-molecular-weight, melt-spun, aliphatic flexible-chain polymer fibers (e.g., polyethylene, polypropylene, polyester, nylon, etc.) are much lower than those of high-cost, high-performance, wholly-aromatic polymer fibers (e.g., Kevlar<sup>®</sup> 49, DuPont and Twaron<sup>®</sup>, Teijin) and ultra-high-molecular-weight, solution-spun, aliphatic polymer fibers (e.g., Spectra<sup>®</sup>, Allied Signal Honeywell and Dyneema<sup>®</sup>, DSM). The great challenge for fiber science and technology is to fill this gap by producing industrially a new generation of low-cost, high-performance polymer fibers (most probably, aliphatic flexible-chain, regular-molecular-weight, melt-spun) with substantially improved tensile and other physical properties. This can be done by introducing the results of the lab-scale research efforts (mentioned above) to the industry. It would be extremely attractive to achieve in the high-throughput industrial process (i.e., with take-up speed  $V_{take-up}$  ranging from several hundred to several thousand meters per minute) fiber tenacity of about 1-2 GPa (12-22 gpd) and initial tensile modulus of about 20-100 GPa (250-1000 gpd) for different aliphatic flexible-chain polymer fibers having different theoretical values of tensile properties. In the work of Taylor and Clark mentioned above, tenacity about 1 GPa and initial modulus 22 GPa where achieved for melt-spun, regular-molecular-weight polypropylene filaments in the lab-scale experiments (see Table V below).

Any company that makes progress in this area will have a tremendous advantage in competition today and in the future. To the best of our knowledge, no significant progress in this area has been so far achieved by the American, Japanese, and European fiber industries.

A few attempts were made in the prior art to improve conventional industrial drawing methods.

A method and apparatus for incremental drawing of fibers on the industrial scale were introduced in U.S. Pat. No. 2,372,627 to Goggin et al. (1945), in U.S. Pat. No. 2,788,542 to Swalm et al. (1957) and in U.S. Pat. No. 3,978,192 (1976), 4,891,872 (1990), 4,980,957 (1991), 5,339,503 (1994), and 5,340,523 (1994), all to Sussman. The incremental drawing improves the conventional commercial drawing process by dividing it into small steps, typically 10-30, i.e., fibers are drawn on microterraced or smooth surfaces of a pair of conical rollers with canted axes.

U.S. Pat. No. 4,967,457 to Beck et al. (1990) disclosed an arrangement for stretching thermoplastic fibers. In this patent fiber moves through a plurality of non-driven rollers arranged between the delivery mechanism and the stretching mechanism inside the heat chamber. Some rollers have brakes providing several successive stretching zones.

Both invented methods provide longer drawing path and drawing time T as well as lower strain rate  $V_{strain}$  in comparison with conventional methods. However, as in the conventional drawing methods the fiber, while being drawn, passes the drawing apparatuses at high speed and at the end of the drawing stage  $V_{fiber2} = V_{outlet}$  (in other words, the ratio of outlet speed  $V_{outlet}$  to fiber speed  $V_{fiber2}$  is 1 to 1). If after the drawing stage the drawn fiber is conveyed to the receiving package,  $V_{fiber2} = V_{outlet} = V_{take-up}$ . Economical reasons force to keep speeds  $V_{fiber2}$ ,  $V_{outlet}$ , and  $V_{take-up}$  as high as possible, i.e., in the range from several hundred to several thousand m/min, in order to provide high throughput.

For both methods the “impulsive” acceleration, although reduced, still remains high at each drawing step or zone. In the case of high-throughput processes, the drawing is non-equilibrium, i.e., it still has short drawing time (a few seconds), which is not enough to heat the fiber (especially high-denier fiber) to the ambient temperature in the process of drawing. In the case of the incremental drawing, the fiber is drawn only between rollers and not on their surfaces while traveling through the drawing apparatus. This results in reduction of drawing time to the level, which can reach about half of the residence time in the apparatus. The drawing starts and stops

while the fiber moves through the drawing apparatus. Thus, the incremental drawing is not uniform and may be termed “intermittent drawing”.

A technology for winding fiber ~~in-controlled~~ into coiled loops around a conveyer device, conveying these fiber loops at a slow speed and high residence time through a heat chamber by this conveyer device, then unwinding these fiber loops, and taking up the fiber with high speed has been proposed for fiber heat setting in U.S. Pat. No. 3,426,553 to Erb (1969), U.S. Pat. No. 3,774,384 to Richter (1973), U.S. Pat. No. 4,414,756 to Simpson et al. (1983), U.S. Pat. No. 5,522,161 to Vetter (1996), and U.S. Pat. No. 5,588,604 to Vetter et al. (1996). However, the invented method and apparatuses were not designed for and capable of fiber drawing.

U.S. patent 2,302,508 to Sordelli (1942) disclosed an apparatus substantially in the form of a winding frame having the general form of a frustum of a cone, which upon being set rotating about its axis promotes the winding of the filament material in a series of helical turns distributed over the apparatus from its end having the minimum diameter towards the opposite end having the maximum diameter. The filament material winds up in a continuous manner onto the apparatus and unwinds therefrom after it has traveled along the said series of turns; during the movement the material undergoes a continuous progressive stretching action, whereby it increases in length to an extend which depends upon the structural characteristics of the apparatus. The winding frame comprises a carrier member rotating about a central axis and a plurality of cantilever rollers each rotatably mounted at one end at said carrier member, the axes of said rollers being both diverged and skewed with respect to the central axis. The skewed rotated rollers draw the fiber by expending the helical turns while conveying these turns along the central axis.

In this invention, the fiber passes the drawing apparatus at low speed providing longer drawing path and drawing time T as well as lower strain rate  $V_{strain}$  in comparison with conventional industrial drawing processes. However, this apparatus has some disadvantages to be implemented on the industrial scale. They are as follows:

(1) It is complicated in design having the diverged and skewed cantilever driven rollers rotated about their axes and simultaneously about the central axis as a parts of the winding rotating frame.

(2) The apparatus has a fixed divergency of the rollers and is not capable to change the fiber draw ratio, if it is necessary, by changing the divergency.

(3) The conveyer-drawing members (which are cantilever, diverged, and skewed with respect to the central axis) are not strong enough to sustain high drawing forces in the drawing process while drawing large number of the fiber loops (up to a few hundreds) especially in case of high draw ratios (e.g., 5x and higher), high denier filaments, and present-day high tenacity fibers. Large number of loops (100-200 and higher) is necessary to provide long drawing time  $T$  and low strain rate  $V_{strain}$  at high outlet speed  $V_{outlet}$  and throughput. For the same reasons, Sordelli's apparatus has limitations to be long to place large number of the loops. Sordelli's apparatus has also limitations to provide high divergency of the conveyer-drawing members and large diameter of the leading fiber loop at the delivery end necessary for high draw ratios (5x and higher) because of design of the driving mechanism (gear box) to drive the conveyer-drawing members and possibility of sliding down of the fiber loops along the conveyer-drawing members (see below).

(4) In Sordelli's apparatus, the conveyer-drawing members (rollers) have smooth surface covered with rubber or other materials to improve friction and to prevent sliding down of the fiber loops on the surface of the members. In this case, it would be difficult to find the coverage that can operate inside a heat chamber at elevated temperatures necessary for effective hot drawing of the fibers. Without the coverage, it is quite possible that the loops will slide down the conveyer-drawing members especially in case of (i) the higher divergency of the conveyer-drawing members necessary for higher draw ratios, (ii) some polymers with lower friction coefficient, and (iii) some finishes applied in the fiber making process.

(5) Sordelli's apparatus is not operator-friendly, i.e., it is difficult to load the fiber end into the apparatus to start the drawing process as well as to restart the apparatus after fiber breakage, and, in case of fiber breakage, the broken ends can be easily wound on the rotated rollers resulting in significant operational problem.

Thus, the Sordelli's apparatus has substantial disadvantages to be industrially feasible.

## BRIEF SUMMARY OF THE INVENTION

This invention relates to a method and apparatus for low-fiber-speed, low-drawing-speed, high-throughput, uniform, continuous drawing of fibers, or like flexible elements formed from natural resins, synthetic resins, or combination of both, in the form of coiled fiber loops. As mentioned above, the coiled fiber loops are a connected set of rings or twists into which the fiber can be wound.

The fiber is fed at an inlet speed to the drawing apparatus, which includes a conveyer-drawing structure comprising a plurality of conveyer-drawing members (e.g., rotating threaded spindles or circulating endless chains) disposed about a central axis. The conveyer-drawing members have receiving ends and delivery ends spaced along the central axis and diverge from this axis in such a way that the distance between the delivery ends and the central axis is greater than the distance between the receiving ends and the central axis. The controlled coiled fiber loops are continuously laid around on the receiving ends of the moving conveyer-drawing members by a feed device ~~fiber winding flyer which rotates about the central axis~~. Thus, a layer consisting of coiled fiber loops is formed about on the conveyer-drawing members. The conveyer-drawing members draw the fiber by expending the circumference of the fiber loops while slowly conveying these loops along the central axis from the receiving ends to the delivery ends. Preferably, the fiber coil is slowly rotated about the central axis preventing the fiber loops from having permanent contact points with the conveyer-drawing members.

The coiled fiber loops, while being conveyed and drawn, are subjected to elevated temperature using heat chamber supplied with hot air, hot inert gas or superheated steam.

At the delivery ends, leading loops of the drawn fiber are successively removed by a take-off device. ~~comprising a fiber unwinding flyer which rotates about the central axis~~. The fiber is conveyed either to a next stage of the fiber making process or to a receiving package at outlet speed  $V_{outlet}$  ranging from several hundred to several thousand meters per minute.

In comparison with existing industrial processes, the invented drawing process has one or more of following advantages: significantly longer drawing time  $T$ , lower strain rate  $V_{strain}$ , and lower tension in the drawing line at the same or higher fiber speeds  $V_{outlet}$  and  $V_{take-up}$  and throughput. This opens the door for substantial improvement of physical properties of commercial fibers, less breaks, less equipment stops, and less waste in comparison with the prior art in industrial fiber technology.

## OBJECTS OF THE INVENTION

It is an object of the present invention to provide a new method and apparatus for continuous drawing of polymer fibers that avoid the disadvantages of the prior art.

1. It is an object of the present invention to provide a new industrial method and apparatus for continuous fiber drawing which meet two requirements that are considered incompatible by the fiber industry, in particular in the area of melt-spun aliphatic flexible-chain polymer fibers:
  - (a) requirement of the fiber industry -- to have high outlet speed  $V_{outlet}$  and take-up speed  $V_{take-up}$  ranging from several hundred to several thousand meters per minute to provide high throughput, and
  - (b) requirement of the polymer fiber science -- to provide long drawing time  $T$  and low strain rate  $V_{strain}$  which are necessary to achieve the efficient “low oriented - high oriented polymer system transition” and to produce high-performance fibers. Drawing time  $T$  needs to be long enough (i.e., ranging from several seconds to several tens of seconds) to heat the fiber in the drawing process to the ambient elevated temperature with low temperature gradient and uniform morphology and physical properties in the fiber cross-section. Strain rate  $V_{strain}$  needs to be at least one to two orders of magnitude lower than that in the industrial processes (i.e., ranging from several %/sec to several tens of %/sec).

2. Another object of the present invention is to provide a new industrial method and apparatus for continuous drawing of polymer fiber (both aliphatic flexible-chain and wholly-aromatic) capable of substantially improving fiber tensile properties (i.e., tenacity, Young modulus, intermediate moduli, breaking elongation, etc.) approaching those obtained in laboratory experiments at low strain rate  $V_{strain}$  and long drawing time  $T$ . In particular, this will result in development of a new generation of low-cost, high-performance industrial polymer fibers (most probably melt-spun, regular-molecular-weight, aliphatic flexible-chain) having tenacity of about 1-2 GPa (12-22 gpd) and initial tensile modulus of about 20-100 GPa (250-1000 gpd) for different polymer fibers having different theoretical values of tensile properties.

3. Another object of the present invention is to provide a more reliable industrial process for continuous fiber drawing without abrupt, "impulsive" acceleration. This process will result in lower tension in the drawing line, less breaks, less equipment stops, and less waste than in the prior art.

4. An additional object of the present invention is to provide a new industrial method and apparatus for continuous fiber drawing which will produce dimensionally stable, low-shrinkage fibers without using expensive and energy-consuming additional equipment, while retaining improved physical properties, such as initial modulus, intermediate moduli, and tenacity, mentioned above. This may result in substantial saving in capital expenses, energy consumption, and possibility of smaller industrial space.

5. A further object of the present invention is to develop a new industrial method and apparatus for continuous fiber drawing (a) providing, in some cases, a substantial increase in the throughput in comparison with the existing industrial processes by increasing outlet speed  $V_{outlet}$  and take-up speed  $V_{take-up}$  and (b) maintaining existing or improved physical properties, such as initial modulus, intermediate moduli, tenacity, and shrinkage, mentioned above.

6. To accomplish the objects mentioned above, it is an object of the present invention to develop a new industrial method and apparatus for continuous fiber drawing which provide a ratio

of outlet speed  $V_{outlet}$  to a fiber speed  $(V_{fiber})_{max}$  substantially greater than 1 to 1 (i.e., preferably in the range from about 10 to 1 to about 6000 ~~9000~~ to 1), fiber speed  $(V_{fiber})_{max}$  being the highest value of fiber speed  $V_{fiber}$  in the drawing process. In the prior art discussed above, fiber speed  $(V_{fiber})_{max}$  is fiber speed at the end of the drawing stage  $V_{fiber2}$  which equals  $V_{outlet}$ . Thus, in the prior art the ratio of  $V_{outlet}$  to  $(V_{fiber})_{max}$  is 1 to 1 (if a relaxation stage follows the drawing stage, this ratio can be slightly lower than 1 to 1, e.g., 0.97 to 1).

Still further objects and advantages will become apparent from the consideration of the ensuing description and drawings.

#### BRIEF DESCRIPTION OF THE DRAWINGS

In the drawings, closely related figures have the same number but different alphabetic suffixes.

Fig. 1A is a longitudinal view illustrating one embodiment of the present invention where the conveyer-drawing members are rotating threaded spindles;

Fig. 1B shows, in schematic sectional view taken on line I-I in Fig. 1A, threaded spindles arranged in an isosceles hexagon;

Fig. 1C shows, in schematic sectional view taken on line II-II in Fig. 1A, chain wheels for rotating threaded spindles arranged in an isosceles hexagon;

Fig. 2A is a longitudinal view illustrating another embodiment of the present invention where each conveyer-drawing member consists of several circulating endless chain sections;

Fig. 2B is a fragmentary, schematic plan view illustrating the conveyer-drawing chain arrangement of the embodiment of Fig. 2A;

Figs. 2C is a fragmentary schematic views of the conveyer-drawing chains in Fig. 2A having fiber displacing members comprising guide semi-rings for controlling the fiber loop positioning;

Fig. 2D is a fragmentary sectional view taken on line I-I in Fig. 2A showing a driving line for the conveyer-drawing chains, with some parts omitted for the sake of clarity;

Fig. 3A is a longitudinal view illustrating another embodiment of the present invention where each conveyer-drawing member consists of a pair of parallel circulating endless chains;

Fig. 3B shows, in schematic sectional view taken on line I-I in Fig. 3A, pairs of chains arranged in an isosceles hexagon;

Fig. 3C is a fragmentary view of rollers mounted on the conveyer-drawing chains for embodiment of Fig. 3A;

Figs. 3D is a fragmentary view of rollers mounted on the conveyer-drawing chains for embodiment of Fig. 3A;

Fig. 3E is a fragmentary sectional view taken on line II-II in Fig. 3A showing a driving line for conveyer-drawing chains, with some parts omitted for the sake of clarity;

Fig. 3F is fragmentary view showing a driving line for the rollers supporting the fiber loops;

Fig. 3G is a fragmentary sectional view taken on line III-III in Fig. 3A, with some parts omitted for the sake of clarity;

Figs. 4 and 5 are schematic views of increase of fiber loop circumference from  $L_i$  to  $L_{i+1}$  while the loop passes distance  $d$  along the central axis that takes time  $\Delta t \Delta T$ ;

Fig. 6 shows linear speeds of fiber points in the case of the rotation of the fiber coil about the central axis clockwise by rotating spindles or rollers; and

Fig. 7 shows stress-strain behavior of polypropylene fibers drawn by the invented method:  
a - sample 1, b - sample 4 from Tables III-V, c - conventional commercial technology.

## Reference Numerals in Drawings

11	heat chamber	55	shaft
12,14	supporting housings	56	chain wheel
13,15	bearings	58	chain
16,18	supporting bearings	59	shaft
20, 21	drive shafts	60	chain wheel
20a	first inner guide channel	61	universal joint
21a	third inner guide channel	62, 62', 62"	radial arms
22	<u>fiber winding</u> <u>fiber-winding</u> flyer	66, 66a, 66b	chain sections
22a	outlet (of the <u>fiber winding</u> <u>fiber-winding</u> flyer)	68	chain wheel
22b		69	shaft
24	second inner guide channel	68'	double guide chain wheel
	<u>fiber unwinding</u> <u>fiber-unwinding</u> flyer	70, 70', 70"	radial arms
		71, 71', 71"	radial arms
24a	inlet (of the <u>fiber unwinding</u> <u>fiber-unwinding</u> flyer)	72	beveled gear
		74	beveled gear
24b	fourth inner guide channel	76a, 76b	fiber displacing members
25, 25a	driving gears	77	guide semi-ring
G	fiber	78, 78', 78"	supporting parts
26	feed roller	80	chain
27, 27a	electric motors	82	shaft
28	conveying roller	84, 86	beveled gears
28'	roller	88	shaft
30	weight	90	long gear
32	tubular support	92	shaft
34	first sun gear	96	supporting part
35	planetary carrier	98	roller
36, 38	shafts	98a	circumferential groove
40,42	planetary pinions	100	gear
44	second sun gear	102	ball bearing
46, 48	radial arms	104	shaft
49	radial arm	106, 106a	pins
50	guide slot		
52,53	bearings		
54	spindle		
54a, 54b	shaft portions		

## DETAILED DESCRIPTION OF THE INVENTION

This invention is further illustrated by the following embodiments, which are not to be construed in any way as imposing limitations upon the scope thereof. On the contrary, it is to be clearly understood that resort may be had to various other embodiments, modifications, and

equivalents thereof, which, after reading the description herein, may suggest themselves to those skilled in the art without departing from the spirit of the present invention and/or the scope of the appended claims.

Figs. 1A-1C – One Embodiment.

One embodiment of the invention for continuous drawing of fibers in form of coiled fiber loops is illustrated in Figs. 1A-1C. Fig. 1A shows a longitudinal view of an invented apparatus for the fiber drawing which has the following main parts: (a) a conveyer-drawing structure for conveying and simultaneous drawing a fiber G in the form of coiled fiber loops, (b) a feed device for feeding fiber G to the conveyer-drawing structure at an inlet speed and laying successive, controlled coiled fiber loops around the conveyer-drawing structure at the beginning of the fiber drawing, (c) a take-off device for taking continuously off the leading fiber loops from the conveyer-drawing structure at the end of the fiber drawing and conveying the drawn fiber from the fiber drawing apparatus either to the next stage of the fiber making process or to the receiving package at an outlet speed, (d) a driving mechanism for driving parts of the conveyer-drawing structure, the feed device, and the take-off device, and (e) a heat chamber 11 for heating fiber G while the fiber being conveyed and drawn. For a detailed description see below.

(a) The conveyer-drawing structure comprises six spindles 54 comprising shaft portions 54a and 54b and a thread or a spiral groove. The spindles are disposed about a central axis and have receiving ends for receiving the fiber and delivery ends for delivering the fiber and both the receiving ends and the delivery ends are spaced along the central axis. The delivery ends are spaced further from the central axis than the receiving ends. Spindles 54 are arranged in an isosceles hexagon when viewed in the cross-section (Fig. 1B) and positioned at a variable changeable divergence angle  $\alpha$  (the same for all spindles) to the central axis.

The conveyer-drawing structure comprises supporting housings 12 and 14, supporting bearings 16 and 18, bearings 13 and 15, bearings 52 and 53, drive shafts 20 and 21, a tubular support 32 (composed of two parts), and radial arms 46, 48, 62, 62', and 62" (six of each arm). The radial arms are arranged in an isosceles hexagon when viewed in the cross-section

section. Bearings 16 and 18, which are mounted in housings 14 and 12 respectively, support one end of shaft 20 and one end of shaft 21 respectively. Two bearings 13 and two bearings 15 are mounted in tubular support 32. They support shafts 21 and 20 respectively. Support 32 supports radial arms 46, 48, 62, 62', and 62''. Arms 48 support bearings 52. Bearings 52 can be moved along and secured in guide slots 50 in arms 48, angle  $\alpha$  of spindles 54 being changed. Arms 62 support bearings 53. Bearings 53 and 52 support shaft portions 54a and 54b of spindles 54 respectively. Arms 62' and 62'' support spindles 54 to prevent sagging.

The conveyer-drawing structure comprises a stabilizing mechanism which prevents rotation of the conveyer-drawing structure (to put it more precisely, its parts supported by tubular support 32) about the central axis. The stabilizing mechanism is located at the receiving ends of spindles 54. It comprises a planetary carrier 35, shafts 36 and 38, a pair of planetary pinions 40, a pair of planetary pinions 42, a first sun gear 34, and a second sun gear 44.

Planetary carrier 35 is secured to shaft 20, shafts 36 and 38 are mounted on carrier 35 for rotation, planetary pinions 40 are secured to shaft 36, planetary pinions 42 are secured to shaft 38, first sun gear 34 is secured to tubular support 32, and second sun gear 44 is secured supporting housing 14.

(b) The feed device comprises a pair of driven feed rollers 26, a fiber-winding fiber-winding flyer 22, an outlet 22a, a first inner guide channel 20a, a second inner guide channel 22b, a polytetrafluoroethylene tube (not shown), carrier 35, and shaft 20 (carrier 35 and shaft 20 are also parts of the conveyer-drawing structure, see above). Flyer 22 is secured to carrier 35 at the receiving ends of spindles 54. Flyer 22 has outlet 22a at its free end and second guide channel 22b communicating with first guide channel 20a passing through the end portion of shaft 20 and planetary carrier 35. The polytetrafluoroethylene tube (not shown) is inserted into channels 20a and 22b up to outlet 22a, the fiber passing through the channels with very little friction.

(c) The take-off device comprises a pair of driven conveying rollers 28, a roller 28', a weight 30, an fiber-unwinding fiber-unwinding flyer 24, an inlet 24a, a third inner guide channel 21a, a fourth inner guide channel 24b, a polytetrafluoroethylene tube (not shown), and shaft 21 (it is

also a part of the conveyer-drawing structure, see above). Flyer 24 is secured to shaft 21 at the delivery ends of spindles 54. Flyer 24 has inlet 24a at its free end and fourth guide channel 24b communicating with third guide channel 21a passing through the end portion of shaft 21. Roller 28' supports weight 30. The polytetrafluoroethylene tube (not shown) is inserted into channels 21a and 24b up to inlet 24a, the fiber passing through the channels with very little friction.

(d) The driving mechanism comprises electric motors 27 and 27a, driving gears 25 and 25a, shafts 20 and 21 (they are also parts of the conveyer-drawing structure, the feed device, and the take-off device, see above), six chain wheels 56, a chain wheel 60, a chain 58, universal joints 61, shafts 55, a shaft 59, and an adjustable transmission (not shown). Gear 25 is secured to shaft 20, and gear 25a is secured to shaft 21. Chain wheels 56 are secured to shafts 55 mounted in arms 46 for rotation. Chain wheel 60 is mounted on shaft 59 for rotation and connected by the adjustable transmission (not shown) to shaft 20 (Fig. 1C). Shaft 59 is secured to arm 46. Chain 58 passes over wheels 56 and wheel 60. Universal joints 61 are mounted on the other ends of shafts 55 and connected to shaft portions 54a of spindles 54 (Figs. 1A and 1C).

(e) Heat chamber 11 envelopes the conveyer-drawing structure (besides supporting housings 12 and 14 and bearings 16 and 18), the winding and unwinding flyers, and the driving mechanism besides motors 27 and 27a and gears 25 and 25a. It is supplied with hot air, hot inert gas, or superheated steam.

Figs. 1A-1C – Operation.

Electric motor 27 rotates gear 25 and hence rotates shaft 20 in bearing 16 and two bearings 15. Shaft 20 rotates carrier 35 with flyer 22, shafts 36 and 38, and pinions 40 and 42 about the central axis. Pinions 40 and 42 roll on sun gears 34 and 44 preventing support 32 from turning about shaft 20 and the central axis. Thus the parts of the conveyer-drawing structure supported by tubular support 32 are prevented from rotation about the central axis. Electric motor 27a rotates gear 25a and hence rotates shaft 21 in bearing 18 and two bearings 13. Shaft 21 rotates flyer 24 about the central axis.

Spindles 54 are rotated by means of electric motor 27a, gear 25a, shaft 21, the adjustable transmission (not shown), wheel 60, chain 58, wheels 56, shafts 55, and universal joints 61. Shaft portions 54a and 54b of spindles 54 rotate in bearings 53 and 52, respectively.

Fiber G comes to feed rollers 26 at an inlet speed either from a previous stage of the fiber making process (e.g., spinning, previous stage of drawing, etc.) or from a feeder package. The fiber passes through channels 20a and 22b and comes out of outlet 22a. Flyer 22 rotates with shaft 20 and carrier 35 and lays successive, controlled coiled fiber loops about the receiving ends of rotating spindles 54. Spindles 54 are rotated in such a direction that the newly laid fiber loops travel to the left along the central axis, as viewed in Fig. 1A, freeing room for the next laid fiber loop. A layer of the coiled fiber loops is formed around spindles 54. The spindle thread or spiral groove serves as a fiber displacing member providing the fiber loop conveying along the central axis and the fiber drawing.

Both flyers 22 and 24 make one revolution while spindles 54 make one revolution. As this takes place, each fiber loop travels along the central axis one pitch of the fiber coil. Simultaneously the fiber coil is slowly rotated about the central axis by the rotating spindles, and each point of the fiber loop passes along the loop circumference a distance equal to a spindle circumference (measured at inner diameter of the thread or spiral groove). The loops increase their circumference with each spindle revolution, the fiber gradually being drawn by rotating spindles 54 at the heat chamber temperature. The leading fiber loops are continuously unwound by flyer 24 at the delivery ends of spindles 54. The corresponding length of the fiber is conveyed through inlet 24a and guide channels 24b and 21a by the conveying rollers 28 and roller 28'. The fiber is conveyed either to the next stage of the fiber making process or, through a winder (not shown), to the receiving package (not shown). The fiber does not have permanent contact points with the spindles. This provides the uniformity of the dimensions and physical properties of the drawn fiber.

For the invented method and apparatus, the fiber draw ratio  $\lambda$  equals the ratio of the loop circumference at the delivery ends to that at the receiving ends. It can be changed by moving bearings 52 along guide slots 50 in arms 48 and securing them there, angle  $\alpha$  of spindles 54

being changed. This results in changing the loop circumference at the receiving ends. Heights of arms 62' and 62" supporting spindles 54 are adjusted when angle  $\alpha$  is changed. The fiber, while being fed to and taken off the spindles, is under tension and cannot shrink because feed rollers 26 and conveying rollers 28 with roller 28' and weight 30 carry out tension control along with additional tension control devices (not shown) placed before and after the whole apparatus.

Figs. 2A-2D -- Another Embodiment

The embodiment illustrated in Figs. 2A-2D corresponds to the embodiment of Figs. 1A-1C and corresponding parts have the same reference numbers. In the conveyer-drawing structure spindles 54 (Fig. 1A) are replaced with the same number (six) of circulating chain members arranged in an isosceles hexagon when viewed in the ~~cross section~~ cross-section. Each chain member is subdivided into three separate endless circulating chain sections 66, 66a, and 66b, which pass over chain wheels 68 and double guide chain wheels 68' (Figs. 2A and 2B).

All chains have a plurality of displacing members 76a and 76b. Each chain link has either displacing member 76a or displacing member 76b (Fig. 2C). Each displacing member comprises a guide semi-ring 77 for fiber support. For the sake of clarity, we do not illustrate the displacing members over all the chain sections in Fig. 2A. Wheels 68 are mounted on radial arms 48 and 70, and wheels 68' are mounted on radial arms 70' and 70" for rotation. Arms 70 support shafts 69, which carry wheels 68 and beveled gears 74 (Fig. 2D). Gears 74 are engaged with beveled gears 72 carried by shafts 55 which is mounted on arm 46 for rotation (Figs. 2A and 2D). Wheels 68 can be moved along and secured in guide slots 50 of arms 48, divergence angle  $\alpha$  between the chain sections and the central axis being changed. Heights of arms 70' and 70" are adjustable, and the arms can be moved and secured along support 32. Angle  $\alpha$  is the same for each chain section 66, 66a, or 66b, but can be either different or the same for different sections. The chains slide along supporting parts 78, 78', and 78" to prevent chain sagging under drawing forces. These parts are stationary, supported by arms 48, 70', 70", and 70, and their inclination angle with respect to the central axis can be changed along with the change of angle  $\alpha$  for each chain section.

As shown in Figs. 2A and 2B, sections 66, 66a, and 66b pass over double guide chain wheels 68' so that the delivery end of each chain section overlaps with the receiving end of the next chain section. Since adjacent receiving and delivery ends are circumferentially spaced, they support different portions of the fiber loops moved by the circulating chains along the central axis.

This changes contact points between the fiber and the fiber displacing members thus resulting in better uniformity of dimensions and physical properties of the drawn fiber.

#### Figs. 2A-2E -- Operation

The chains are driven by means of electric motor 27a, gear 25a, shaft 21, the adjustable transmission (not shown), wheel 60, chain 58, wheels 56, gears 72 and 74, and wheels 68 and 68' (Figs. 2A, 2B, and 2D). Both flyers 22 and 24, rotated in opposite directions, make one revolution while chains 66, 66a, and 66b move one chain pitch. Flyer 22 lays ~~controlled~~ coiled fiber loops about the receiving ends of chains 66 placing each loop in contact with guide semi-rings 77 of displacing members 76a and 76b (Fig. 2C) which facilitate the fiber loop conveying along the central axis and the fiber drawing. The rest of the operation is the same as in the case of the embodiment of Fig. 1A.

#### Figs. 3A - 3G -- Another Embodiment

The embodiment illustrated in Figs. 3A-3G corresponds to the embodiments of Figs. 1A-2D and corresponding parts have the same reference numbers. In the conveyer-drawing structure, the six chains having sections 66, 66a, and 66b (Fig. 2A) are replaced by six pairs of parallel circulating endless chains 80 which are not subdivided in three separate section each as in the embodiment of Figs. 2A. These six chain pairs are arranged in an isosceles hexagon when viewed in the cross-section (Fig. 3B). They pass over wheels 68 at both the receiving and delivery ends. The chains slide along supporting parts 96 to prevent chain sagging under drawing forces. These parts are stationary, supported by radial arms 71, 71', 71", and 49,

and their inclination angle with respect to the central axis can be changed along with the change of divergence angles  $\alpha$  of chains 80.

Displacing members are mounted on the parallel chains. They comprise rollers 98 having circular circumferential grooves 98a, pins 106 and 106a, shafts 104, and ball bearings 102 (Figs. 3C and 3D). Each pair of the parallel chains is joined by pins 106 and 106a. Each pair of chain links (one link from each chain) is joined by either two pins 106 or two pins 106a. Lateral parts of the chains are modified to support the pins. Each pair of pins 106 and 106a supports a shaft 104 which carries roller 98 with ball bearing 102. The axes of shafts 104 are adjusted nearly parallel to the central axis of the drawing apparatus while the fiber draw ratio is changed by varying divergence angle  $\alpha$  of chains 80. To achieve this, the angle between shafts 104 and the chain is adjusted for each roller 98 by rotating shafts 104 around pins 106 and 106a. Other pins 106 and 106a are moved along and secured to the side portions of the chains (Fig. 3C). Gears 100 are attached to each side of rollers 98. For the sake of clarity we did not illustrate rollers 98 over all chains 80 in Fig. 3A.

Each shaft 82 mounted in arm 70 71 carries two wheels 68, a beveled gear 84, beveled gear 74, and supports one end of a shaft 88 (Figs. 3E and 3F). Beveled gears 84 are engaged with beveled gears 86 fastened to long gears 90. Gears 86 and 90 are mounted on shafts 88 (Fig. 3F). Gears 90 are engaged with gears 100 of rollers 98 (Figs. 3C-3F). The other end of shaft 88 is supported by shaft 92 (Fig. 3G). Shafts 92 are supported by arms 49 and can be moved along and secured in guide slots 50. As this takes place, shafts 88 turn around shafts 82, and gears 86 roll around gears 84, both gears remaining engaged. Two wheels 68 are mounted on each shaft 92 (Fig. 3G).

#### Figs. 3A - 3G -- Operation

Chains 80 are driven by means of electric motor 27a, gear 25a, shaft 21, the adjustable transmission (not shown), wheel 60, chain 58, wheels 56, gears 72 and 74, and wheels 68 (Figs. 3A and 3E). At the same time gears 84 rotate gears 86 and long gears 90 (Figs. 3E and 3F). Gears 90 rotate gears 100 and rollers 98 while rollers 98 are moved by chains 80 from the receiving ends, along gears 90, to the delivery ends. Flyers 22 and 24, rotated in opposite

directions, make one revolution while chains 80 move one chain pitch. Flyer 22 lays ~~controlled~~ coiled fiber loops about the receiving ends of chains 80 placing each loop in grooves 98a of rollers 98 (Fig. 3C and 3D) and forming the layer of coiled fiber loops supported by the rollers. Rollers 98, as a part of the displacing members, facilitate the fiber loop conveying along the central axis and the fiber drawing. As the fiber loops travel to the left along the central axis, as viewed in Fig. 3A, the fiber coil is rotated about the central axis by rotating rollers 98. This changes contact points between the fiber and the rollers thus resulting in a better uniformity of dimensions and physical properties of the drawn fiber. Rotation speed of rollers 98 and the fiber coil is adjustable. The rest of the operation is the same as in the case of embodiments of Figs. 1A and 2A.

The apparatus can be used with rollers 98 not being rotated by the driving mechanism. In this instance, the coiled fiber loops, supported by free-to-rotate rollers, are not rotated about the central axis. In some cases, this is sufficient to produce the drawn fiber having uniformity of the dimensions and physical properties along the fiber axis.

## CALCULATIONS

As discussed above, ~~in contrast to the prior art~~, the invented continuous drawing method provides that fiber linear speed  $(V_{fiber})_{max}$  in the drawing process is substantially lower than outlet speed  $V_{outlet}$  (the ratio of  $V_{outlet}$  to  $(V_{fiber})_{max}$  is substantially greater than 1 to 1). At the same time, strain rate  $V_{strain}$  is substantially lower and drawing time  $T$  is longer than those in the existing industrial processes without reducing, and in some cases even increasing, the throughput. The following calculations, made for the embodiments of Figs. 1A-3A, support these statements.

The A speed of conveying the fiber loops along the central axis  $V_{loop}$  is given by

$$V_{loop} = d/\Delta t \Delta T \quad \text{and} \quad (6)$$

$$\Delta t \Delta T = d/ V_{loop}, \quad (7)$$

where  $d$  is the a distance between adjacent loops in the fiber coil along the central axis, i.e., a pitch of the fiber coil and

$\Delta t \Delta T$  - time needed for the fiber loop to pass distance  $d$ .

According to the mass conservation rule, in a continuous fiber making process equal fiber mass should pass through any cross-sectional plane (plane perpendicular to the central axis) in a unit time both inside and outside of the apparatus. For the fiber having the same draw ratio  $\lambda$ , the fiber mass is in proportion to the fiber length.

Inside of the apparatus, at the delivery ends, a fiber length  $L$ , which is the a circumference of the leading fiber loop at the delivery ends, passes cross-sectional plane for time  $\Delta t \Delta T$  (see above). Outside the apparatus, while the fiber being conveyed either to the next stage of the fiber making process or to the receiving package, the same length  $L$  of the straightened fiber (having the same  $\lambda$ ) should pass cross-sectional plane for the same time  $\Delta t \Delta T$ . Thus, outlet speed  $V_{outlet}$  is given by

$$V_{outlet} = L / \Delta t \Delta T, \quad (8)$$

Thus, equations (7) and (8) lead to a ratio  $A$

$$A = V_{outlet} / V_{loop} = L / d. \quad (9)$$

Figs. 4 and 5 show, in schematic view, the increase of fiber loop circumference from  $L_i$  to  $L_{i+1}$  while the loop passes distance  $d$  along the central axis that takes time  $\Delta t \Delta T$ . In the cases case of the embodiments of Figs. 1A-3A, the fiber loops are isosceles hexagons and consist of six equal fiber sections (Fig. 5). Each section is drawn between two adjacent conveyer-drawing members. As an example, section KP becomes section FW. The length increase is  $FH + QW$  (lines KH and PQ are perpendicular to line FW;  $FH = QW$ ). Each point of section KP is drawn with at linear speed along the fiber axis  $V_{fiber}$ , which is different for different points of the section. Points K and P have the highest speed  $V_{fiber}$  in the drawing process designated as  $V_{fiberK}$  and  $V_{fiberP}$ . The middle point of section KP has speed  $V_{fiber} = 0$  (for the case where the coiled fiber loops are not

~~rotated about the central axis~~). Thus the highest value of fiber speed  $V_{fiber}$  in the drawing process  $(V_{fiber})_{max}$  is given by

$$(V_{fiber})_{max} = V_{fiberK} = V_{fiberP} = QW/\Delta t \Delta T = (PW \cdot \cos \varphi_1)/\Delta t \Delta T \quad (10)$$

From isosceles triangle POK (Fig. 5) we get

$$\varphi_1 = (180 - \varphi)/2 \quad (11)$$

In the case where  $n$  conveyer-drawing members are arranged in an isosceles polygon, angle  $\varphi$  is given by

$$\varphi = 360/n, \quad (12)$$

From equations (11) and (12) we get

$$\varphi_1 = (180 - 360/n)/2 = 90 \cdot (1 - 2/n) \quad (13)$$

From equations (10) and (13) we get

$$(V_{fiber})_{max} = PW \cdot \cos[90 \cdot (1 - 2/n)] \cdot 1/\Delta t \Delta T \quad (14)$$

From Fig. 4 we get

$$PW = d \cdot \tan \alpha \quad \text{and} \quad (15)$$

$$(V_{fiber})_{max} = d \cdot \tan \alpha \cdot \cos[90 \cdot (1 - 2/n)] \cdot 1/\Delta t \Delta T \quad (16)$$

From equations (6) and (16) we get

$$(V_{fiber})_{max} = V_{loop} \cdot \tan \alpha \cdot \cos[90 \cdot (1 - 2/n)] \quad (17)$$

From equations (9) and (17) we get

$$(V_{fiber})_{max} = V_{outlet} \cdot d \cdot 1/L \cdot \operatorname{tg} \alpha \cdot \cos[90 \cdot (1-2/n)] \quad (18)$$

Thus, fiber speed  $(V_{fiber})_{max}$  is constant during the drawing at given  $V_{outlet}$ ,  $d$ ,  $L$ ,  $n$ , and  $\alpha$ .

Equation (18) leads to a ratio  $B$

$$B = V_{outlet}/(V_{fiber})_{max} = L/\{d \cdot \operatorname{tg} \alpha \cdot \cos[90 \cdot (1-2/n)]\} \quad (19)$$

In the case of rotation of the coiled fiber loops about the central axis by the rotating rollers or spindles (like in the embodiments of Fig. 1A and Fig. 3A), each point of the fiber loop rotates with a linear speed  $V_{rotation}$ , which is a linear surface speed of the rollers or spindles (Fig. 6). ~~speed  $V_{rotation}$  is perpendicular to a radius of rotation, e.g., OP or OK~~. Each point of the fiber loop in the process of the rotation of the loop about the central axis passes a distance  $L_{fiber}$  while the loop as a whole passes distance  $d$  along the central axis for time  $\Delta t$ .

Distance  $L_{fiber}$  is given by

$$L_{fiber} = V_{rotation} \cdot \Delta t \quad (20)$$

From equations (8) and (20) we get

$$L_{fiber} = (V_{rotation}/V_{outlet}) \cdot L \quad (21)$$

During the drawing, while the fiber loop passes from the receiving to delivery ends, each point of the fiber loop in the process of the rotation of the loop about the central axis passes total distance designated as  $L_{total}$ , which is given by

$$L_{total} = L_{fiber} \cdot (N - N') = (V_{rotation}/V_{outlet}) \cdot L \cdot (N - N'), \quad (22)$$

Where  $(N - N')$  is a number of the fiber loops passing the heat chamber for time of drawing  $T$  in case of rotation of the loops about the central axis by the rotating rollers or spindles,

$N$  is a number of the fiber loops in the heat chamber which is given by

$$N = M/d, \quad (23)$$

where  $M$  is a length of the fiber coil along the central axis, and

$N'$  is a number of loops with an average circumference  $L_{\text{average}}$  which have the total circumference equals  $L_{\text{total}}$  (it is a reduction in number of the fiber loops passing the heat chamber for time of drawing  $T$  as a result of the rotation of the loops about the central axis relative to the case without the rotation) and is given by

$$N' = L_{\text{total}} / L_{\text{average}}, \quad (24)$$

where the average circumference  $L_{\text{average}}$  of the fiber loops in the heat chamber is given by

$$L_{\text{average}} = (L + L')/2, \quad (25)$$

where  $L'$  is the circumference of the first fiber loop at the receiving ends.

The draw ratio  $\lambda$  is given by

$$\lambda = L/L' \quad \text{and} \quad (26)$$

$$L_{\text{average}} = (L + L/\lambda)/2 \quad (27)$$

From equations (22) and (24) we get

$$N' = N / (L_{\text{average}}/L_{\text{fiber}} + 1) \quad (28)$$

One can see that the larger the ratio  $L_{\text{average}}/L_{\text{fiber}}$ , the smaller  $N'$  in comparison with  $N$ .

Thus, time of drawing T, which is time needed for each fiber point to pass from the receiving ends to the delivery ends, is given by

$$T = (M - N \cdot d) / V_{\text{loop}} = [A \cdot (M - N \cdot d)] / V_{\text{outlet}} = \\ = [L \cdot (M - N \cdot d)] / (V_{\text{outlet}} \cdot d) \quad (29)$$

~~In the case of the rotation of the fiber coil about the central axis in clockwise direction (Fig. 6), the linear speeds of fiber points K and P along the fiber axis are  $(V_{\text{fiberK}})_{\text{rotation}}$  and  $(V_{\text{fiberP}})_{\text{rotation}}$  respectively, and they are given by~~

~~for point K  $(V_{\text{fiberK}})_{\text{rotation}} = V_{\text{rotation}} \cdot \sin(1 - V_{\text{fiberK}}) \quad (30)$~~

~~$= V_{\text{rotation}} \cdot \sin[90(1 - 2/n)] - V_{\text{fiberK}} \text{ and} \quad (30)$~~

~~for point P  $(V_{\text{fiberP}})_{\text{rotation}} = V_{\text{rotation}} \cdot \sin[90(1 - 2/n)] + V_{\text{fiberP}} \quad (31)$~~

~~$= V_{\text{rotation}} \cdot \sin[90(1 - 2/n)] + V_{\text{fiberP}} \quad (31)$~~

~~The fiber linear speed for point P is higher than that for point K. Thus, in the case of the fiber coil rotation, fiber speed  $(V_{\text{fiber}})_{\text{max}}$  is given by~~

~~$(V_{\text{fiber}})_{\text{max}} = (V_{\text{fiberP}})_{\text{rotation}} = V_{\text{rotation}} \cdot \sin[90(1 - 2/n)] + V_{\text{fiberP}} \quad (32)$~~

Example 1.

Table I gives the results of calculations for the case:  $L = 5500 \text{ mm}$ ,  $V_{\text{outlet}} = V_{\text{take-up}} = 3000 \text{ m/min}$  (the fiber is conveyed to the receiving package after the drawing stage),  $n = 6$ ,  $\lambda = 5 \text{ to } 1$  (400 %), and  $d$ ,  $M$  and  $A$  are variable. The coiled fiber loops are not rotated about the central axis by the rotating rollers or spindles. Take-up speed of 3000 m/min is typical take-up speed for the commercial process for multifilaments and yarns.

### Example 2.

Table II gives results of calculations for the case:  $L = 2000$  mm,  $V_{\text{outlet}} = V_{\text{take-up}} = 500$  m/min (the fiber is conveyed to the receiving package after the drawing stage),  $n = 6$ ,  $\lambda = 5$  to 1 (400 %), and  $d$ ,  $M$  and  $A$  are variable. The coiled fiber loops are not rotated about the central axis by the rotating rollers or spindles. Take-up speed of 500 m/min is typical take-up speed for the commercial process for tape yarns and monofilaments.

### Example 3.

~~In this example, the coiled fiber loops are rotated about the central axis by the rotating spindles or rollers like in the embodiments of Figs. 1A and 3A. In this case, time of drawing  $T$ , fiber linear speed  $(V_{\text{fiber}})_{\text{max}}$ , and strain rate  $V_{\text{strain}}$  need to be corrected, and fiber linear speed  $(V_{\text{fiber}})_{\text{total,max}}$  will be calculated. They are calculated for the case No. 8, Table I for the embodiment of Fig. 1A. For this embodiment, as discussed above,  $L_{\text{fiber}}$  is always equal the spindle circumference (measured at inner diameter of the thread) and is given by~~

$$L_{\text{fiber}} = \pi D_{\text{spindle}} \quad (33)$$

~~where  $D_{\text{spindle}}$  is an inner diameter of the thread of the spindle.~~

~~For the size of  $D_{\text{spindle}} = 40$  mm, as an example, the calculated parameters according to equations (5)-(33)~~

~~are as follows:~~

$$L_{\text{fiber}} = 125.6 \text{ mm},$$

$$V_{\text{rotation}} = 68.5 \text{ m/min}$$

$$L_{\text{average}} = 3300 \text{ mm for } \lambda = 5 \text{ to } 1 (400\%),$$

$$N' = 9.8,$$

$$T = 28.3 \text{ s (compare with 29.2 s in Table I).}$$

$$(V_{\text{fiber}})_{\text{max}} = 0.75 + 68.5 = 69.25 \text{ m/min}$$

$$V_{\text{output}} / (V_{\text{fiber}})_{\text{max}} = 43.3$$

$$V_{\text{strain}} = 14.1 \%/\text{sec}$$

Table I. Results of Calculations for Example 1.

	Length of the fiber coil along the central axis M, mm	Pitch of the fiber coil d, mm	A = $V_{\text{outlet}} / V_{\text{loop}} = V_{\text{take-up}} / V_{\text{loop}} = L/d$	Fiber loop speed $V_{\text{loop}} = 3000/A$ , m/min	Time of drawing T = $M/V_{\text{loop}}$ , sec <sup>*)</sup>	Number of loops in the heat chamber, N=M/d	Linear fiber speed in the drawing process $(V_{\text{fiber}})_{\text{max}}$ , m/min <sup>**)</sup>	B = $V_{\text{outlet}} / (V_{\text{fiber}})_{\text{max}} = V_{\text{take-up}} / (V_{\text{fiber}})_{\text{max}} = 3000 / (V_{\text{fiber}})_{\text{max}}$ , m/min	Strain rate $V_{\text{strain}} = \lambda/T = 400/T$ , %/sec <sup>**</sup>	Divergence angle $\alpha$ for draw ratio $\lambda$ 5 to 1, deg. <sup>**</sup>
1	500	5	1100	2.7	11.1	100	2.0	1500	36	55.7
2	500	7.5	733	4.1	7.3	67	3.0	1000	54.8	55.7
3	500	10	550	5.4	5.6	50	4.0	750	72	55.7
4	1000	5	1100	2.7	22.2	200	1.0	3000	18	36.3
5	1000	7.5	733	4.1	14.6	134	1.5	2000	27.4	36.3
6	1000	10	550	5.4	11.1	100	2.0	1500	36	36.3
7	2000	5	1100	2.7	44.4	400	0.5	6000	9	20.1
8	2000	7.5	733	4.1	29.2	268	0.75	4000	13.7	20.1
9	2000	10	550	5.4	22.2	200	1.0	3000	18	20.1
10	3000	5	1100	2.7	66.6	600	0.34	8956	6	13.7
11	3000	7.5	733	4.1	43.8	400	0.5	6000	9	13.7
12	3000	10	550	5.4	33.3	300	0.65	4512	12	13.7

<sup>\*)</sup> In case of the fiber coil rotation about the central axis, T and  $V_{\text{strain}}$ , and  $(V_{\text{fiber}})_{\text{max}}$  need to be corrected according to equations (29) and (5), and (32) respectively (see Example 3).

<sup>\*\*)</sup> In case of the embodiment with the conveyer-drawing chains consisting of several sections (Fig. 2A), all chain sections have the same divergence angle  $\alpha$ .

Thus, in the cases examined in Examples 1-32, fiber linear speed  $(V_{\text{fiber}})_{\text{max}}$  is low, i.e., 0.1- 4 m/min for Examples 1 and 2 and 69 m/min for Example 3, time of drawing T can reach tens of seconds, strain rate  $V_{\text{strain}}$  is low, i.e., 6-70 %/sec, and the ratio of  $V_{\text{outlet}}$  to  $(V_{\text{fiber}})_{\text{max}}$  is substantially greater than 1 to 1, i.e., varying from the ratio 43 750 to 1 to the ratio 6000 9000 to 1 (the fiber drawing apparatus can be constructed and arranged to provide the ratio, if necessary, lower than 43 750 to 1 and greater than 6000 9000 to 1). In the case of conventional commercial drawing process having the same  $\lambda = 400\%$  and  $(V_{\text{fiber}})_{\text{max}} = V_{\text{fiber2}} = V_{\text{outlet}} = V_{\text{take-up}} = 3000$  m/min., time of drawing T is about 1 second, and  $V_{\text{strain}}$  is substantially higher, i.e., about 400 %/sec.

Table II. Results of Calculations for Example 2.

	Length of the fiber coil along the central axis M, mm	Pitch of the fiber coil d, mm	A = $V_{\text{outlet}} / V_{\text{loop}} = V_{\text{take-up}} / V_{\text{loop}} = L/d$	Fiber loop speed $V_{\text{loop}} = 3000/A$ $500/A$ m/min	Time of drawing T = $M/V_{\text{loop}}$ sec <sup>*)</sup>	Number of loops in the heat chamber, N=M/d	Linear fiber speed in the drawing process $(V_{\text{fiber}})_{\text{max}}$ , m/min <sup>**)</sup>	B = $V_{\text{outlet}} / (V_{\text{fiber}})_{\text{max}} = V_{\text{take-up}} / (V_{\text{fiber}})_{\text{max}} = 3000500 / (V_{\text{fiber}})_{\text{max}}$ , m/min	Strain rate $V_{\text{strain}} = \lambda/T = 400/T$ , %/sec <sup>**</sup>	Divergence angle $\alpha$ for draw ratio $\lambda$ 5 to 1, deg. <sup>**</sup>
1	500	5	400	1.25	24	100	0.34	1492	16.7	28.1
2	500	7.5	267	1.87	16	67	0.50	1000	25	28.1
3	500	10	200	2.5	12	50	0.67	746	33.3	28.1
4	1000	5	400	1.25	48	200	0.17	3030	8.3	14.9
5	1000	7.5	267	1.87	32	134	0.25	2000	12.5	14.9
6	1000	10	200	2.5	24	100	0.34	1492	16.7	14.9
7	1500	5	400	1.25	72	300	0.11	4546	5.6	10.1
8	1500	7.5	267	1.87	48	200	0.17	3030	8.3	10.1
9	1500	10	200	2.5	36	150	0.22	2222	11.1	10.1

<sup>\*)</sup> In case of the fiber coil rotation about the central axis, T and  $V_{\text{strain}}$ , and  $(V_{\text{fiber}})_{\text{max}}$  need to be corrected according to equations (29) and (5), and (32) respectively (see Example 3).

<sup>\*\*)</sup> In case of the embodiment with the conveyer-drawing chains consisting of several sections (Fig. 2A), all chain sections have the same divergence angle  $\alpha$ .

In the invented method, time of drawing T in some cases is so long that it can be decreased by a factor of 1.5-2 remaining sufficiently long (20-40 sec) to perform uniform hot drawing of even high denier fibers. Thus, speeds  $V_{\text{loop}}$ ,  $V_{\text{outlet}}$ , and  $V_{\text{take-up}}$  can be also increased in these cases at least by a factor of 1.5-2, resulting in the 1.5-2-fold increase and more of the throughput. Thus, the take-up speed can be 4500-6000 m/min and more.

## EXPERIMENT -- Drawing of Polypropylene Fibers.

The first version of a prototype of the drawing apparatus was build. The drawing apparatus comprises two endless chains as the conveyer-drawing members, non-driven, free-to-rotate rollers as the guide members of the displacing elements, and a heat chamber supplied with hot air. The feed and take-off devices or mechanisms were not built at this first stage. However, this

type of mechanisms was proved to be feasible and was successively used in the industrial processes for heat setting of polymer fibers discussed above. The heat chamber of this unit was 1000 mm. long.

Polypropylene commercial resin from Amoco Chemical Co. (grade 10-6345) was used. The resin had the following parameters: Melt Flow Rate - 3.1 gm/10 min.,  $M_w = 370,000$ , and MWD = 5.6. It was extruded at 220°C through the 0.5 mm spinneret orifice at very low take-up speed and quenched in a water bath at room temperature. Wide-angle X-ray diffraction pattern revealed that the as-spun fiber produced was unoriented and low-crystalline.

The drawing process was performed in two separate stages using the drawing apparatus twice, at different temperatures. These two stages of drawing represent two different drawing mechanisms occurring on the molecular level. The initial drawing stage converts the undrawn spherulitic as-spun fiber into a fiber with fibrillar structure developed through a necking-down mechanism. The first stage can be rapid. It is followed by the second drawing stage, which is named superdraw. The second drawing stage orients the newly formed fibrillar structure. This stage needs to be much slower to produce polymer fibers with improved physical properties approaching those achieved in lab-scale experiments mentioned above (V. A. Marikhin and L. P. Myasnikova, "Nadmolekulyarnaya Struktura Polymerov", St. Petersburg, Russia, Khimia (1977); V. A. Marikhin and L. P. Myasnikova, Progr. Colloid Polym. Sci., 92, 39-51 (1993); W. N. Taylor and E. S. Clark, Polym. Eng. Sci., 18, 518-526 (1978)). The ~~rapid~~ first stage can be performed effectively by both conventional and the invented drawing methods. The slower second stage needs to be performed by the invented method and apparatus.

The heat chamber was preheated to given drawing temperatures (see Tables III and IV below) with the chains at rest. The front door of the chamber was open, several loops of polypropylene fibers were placed about the receiving ends of the chains and supported by the rollers ~~roller~~ ~~grooves~~ inside of the heat chamber, the chamber door was closed, and temperature was raised to given temperatures for 30-300 seconds (see Tables III and IV). Then the driving electrical motor was turned on, and the chains started to move conveying the fiber loops through the heat chamber and simultaneously drawing the fiber. When the fiber reached the delivery ends of the

chains, the equipment was stopped, the chamber door was opened, and the drawn fiber was cooled down for 20-300 seconds (see Tables III and IV) before being removed.

Tensile properties were measured by an Instron tensile-testing machine. The breaking length was 30 mm, and the lower clamp speed was 50 mm/min. Results can be seen in Table V along with results on shrinkage. Each result is an average of three tests. Results for conventional commercial PP polypropylene fibers are presented for comparison.

Thus the results of the first experiments confirm that the invented method is capable of producing industrial polymer fibers with superior physical properties in comparison with the conventional industrial processes and approaching those generated in the lab-scale experiments. Our results are very close to laboratory results reported in paper of Taylor and Clark (see Table V) for regular-molecular-weight polypropylene fibers, i.e., our samples have tenacity 0.9-1.2 GPa (11-14.5 gpd) and tensile initial modulus 17.7-20.5 GPa (214-248 gpd).

Table III. Drawing Conditions for Polypropylene Fibers, First Stage of Drawing

	$t_4T_1$ , s sec	$T_4t_1$ , °C	$t_2T_2$ , s sec	$T_2t_2$ , °C	$t_3T_3$ , s sec	$\lambda_1$	$(V_{fiber})_{max1}$ , m/min	$V_{strain1}$ , %/sec
1	120	80	52	80	20	7.6	0.24	12.7
2	100	80	50	80	20	7.1	0.25	12.2
3	130	80	56	80	20	7.7	0.22	12.0
4	120	80	52	80	20	7.1	0.24	11.7
5	110	80	58	80	20	7.7	0.22	11.5
6	120	80	54	80	20	7.7	0.23	12.4

 $T_4t_1$  - beginning drawing temperature of the first drawing stage $T_2t_2$  - final drawing temperature of the first drawing stage $\lambda_1$  - draw ratio for the first drawing stage $t_4T_1$  - time of heating the chamber, with the fiber and chains at rest, to temperature  $T_4t_1$  $t_2T_2$  - time of drawing the fiber $t_3T_3$  - time of cooling drawn fiber with the fiber and chains at rest and the chamber door open $(V_{fiber})_{max1}$  - the highest value of fiber speed  $V_{fiber}$  at the first drawing stage $V_{strain1}$  - fiber strain rate at the first drawing stage

Table IV. Drawing Conditions for Polypropylene Fibers, Second Stage of Drawing

	$t_4T_4$ , s sec	$T_3t_3$ , °C	$t_5T_5$ , s sec	$T_4t_4$ , °C	$t_6T_6$ , s sec	$\lambda_2$	$(V_{fiber})_{max2}$ , m/min	$V_{strain2}$ , %/sec	$\lambda =$ $\lambda_1 \times \lambda_2$
1	240	140	168	140	30	2.6	0.03	0.9	19.8
2	300	140	160	140	30	2.6	0.03	1.0	18.5
3	280	155	185	155	30	2.7	0.02	1.1	20.8
4	30	135	30	142	300	2.3	0.15	4.3	16.3
5	40	130	80	139	240	2.4	0.58	1.8	18.5
6	50	133	90	143	240	2.5	0.50	1.7	19.2

 $T_3t_3$  - beginning drawing temperature of the second drawing stage $T_4t_4$  - final drawing temperature of the second drawing stage $\lambda_2$  - draw ratio for the second drawing stage $t_4T_4$  - time of heating the chamber, with the fiber and chains at rest, to temperature  $T_4t_4$  $t_5T_5$  - time of drawing the fiber in the temperature range from  $T_3t_3$  to  $T_4t_4$  $t_6T_6$  - time of cooling drawn fiber with the fiber and chains at rest the chamber door open $(V_{fiber})_{max2}$  - the highest value of fiber speed  $V_{fiber}$  at the second drawing stage $V_{strain2}$  - fiber strain rate at the second drawing stage $\lambda$  - total draw ratio

Table V. Physical Properties of Polypropylene (PP) Fibers

	Tenacity, GPa, (gpd)	Tensile Initial Modulus, GPa, (gpd)	Breaking Elongation, %	<u>Hot-air</u> <u>Hot-Air</u> Shrinkage at 132 °C, %
1	1.2 (14.5)	19.2 (232)	8.0	0
2	0.9 (10.9)	19.1 (231)	6.6	0
3	0.9 (10.9)	20.5 (248)	7.6	0
4	1.1 (13.3)	17.8 (215)	10.2	3
5	0.9 (10.9)	17.7 (214)	7.6	2
6	1.05 (12.7)	18.9 (229)	9.7	2
Commercial PP fibers (Herculon, Marvess)	0.4-0.7*) (5-9)	2.4-3.7*) (29-45)	15-30*)	2-10**)
Lab-scale PP fibers ***)	0.93 (11.2)	22 (266)	6.2	-

\*) Encyclopedia Britannica 2001 (<http://www.britannica.com/eb/article?eu=126288>),  
“Properties and Applications of Prominent Man-Made Fibres”.

\*\*) Low values of the shrinkage could be a result of fiber relaxation or heat setting  
after the drawing discussed above.

\*\*\*) W. N. Taylor and E. S. Clark, Polym. Eng. Sci., **18**, 518-526 (1978). PP resin:  
 $M_w = 277,000$ ,  $MWD = 10$ . Heating medium - silicon oil. First drawing stage:  
initial length - 100 mm,  $V_{fiber1} = 1$  m/min,  $V_{strain1} = 16.7$  %/sec,  $T_{2t_2} = 130$  °C.  
Second drawing stage:  $V_{fiber2} = 0.001$  m/min,  $V_{strain2} = 0.07$  %/sec,  $T_{4t_4} = 130$  °C,  
total  $\lambda = 25$ .

As presented in Tale V, for polypropylene fibers tenacity is increased by a factor of 1.2-3.0, initial modulus is increased by a factor of 4.8-8.5, and breaking elongation is decreased by a factor of 1.5-4 in comparison with conventional industrial processes. This is accompanied by excellent dimensional stability, i.e., hot-air hot-air shrinkage is 0-3 % at 132 °C.

As an example, stress-strain behavior of the samples 1 and 4 from Tables III-V is presented in FIG. 7. In contrast to many commercial PP polypropylene fibers (Fig. 7, curve c), the stress-strain curves do not have the yielding part or plateau, that indicates high intermediate moduli and, probably, low creep.

## ADVANTAGES

From the descriptions, calculations, and results of experiments given above, one or more of following advantages of the invented drawing method and apparatus in comparison with the prior art in industrial fiber drawing processes become evident:

1. The invented method and apparatus provide the fiber drawing in industrial environment at low fiber speed  $V_{fiber}$  and, at the same time, maintain fiber outlet speed  $V_{outlet}$  and fiber take-up speed  $V_{take-up}$  at regular industrial level ranging from several hundred to several thousand meters per minute providing high throughput. The ratio of speed  $V_{outlet}$  to speed  $(V_{fiber})_{max}$  is substantially greater than 1 to 1 ranging from about 10 to 1 to about 6000 9000 to 1. This accomplishment results in some other advantages presented below.
2. The invented method and apparatus provide the uniform fiber drawing in industrial high-throughput process at low strain rate  $V_{strain}$ , i.e., about 6-70 %/sec, and high drawing time  $T$ , i.e., it can reach tens of seconds. This long drawing time is necessary to heat the fiber to the elevated ambient temperature with low temperature gradient in the fiber cross-section during the drawing in order to have uniform morphology and physical properties in the cross-section.
3. The low-strain-rate, long-drawing-time invented method and apparatus provide more reliable industrial process for continuous uniform drawing of polymer fibers without abrupt, “impulsive” acceleration resulting in lower tension in the drawing line, less breaks, less equipment stops, and less waste than in the prior art.

4. The invented method and apparatus for continuous fiber drawing provide high-throughput industrial process producing dimensionally stable, low-shrinkage fibers without using expensive and energy-consuming additional equipment ~~and without reducing while retaining enhanced~~ physical properties, such as initial modulus, intermediate moduli, and tenacity, mentioned above. This may result in substantial saving of capital expenses, energy consumption, and possibility of smaller industrial space.

5. The invented method and apparatus provide industrial continuous process for drawing of polymer fiber (both aliphatic flexible-chain and wholly-aromatic) capable of improving their tensile properties (i.e., tenacity, Young modulus, intermediate moduli, etc.) approaching those obtained in laboratory experiments. This method is the missing link in development of a new generation of low-cost, high-performance industrial polymer fibers (most probably melt-spun, regular-molecular-weight, aliphatic flexible-chain) having tenacity of about 1-2 GPa (12-22 gpd) and initial tensile modulus of about 20-100 GPa (250-1000 gpd) for different polymer fibers having different theoretical values of tensile properties. Thus, for the new generation of industrial melt-spun, aliphatic flexible-chain polymer fibers, tenacity can be by 2.0-3.0 times higher and initial moduli can be by several times higher than those for conventional commercial aliphatic flexible-chain polymer fibers.

6. The invented method and apparatus in some cases can provide a substantial increase in the throughput in comparison with the existing industrial processes by increasing outlet  $V_{outlet}$  and take-up  $V_{take-up}$  speeds and, at the same time, maintaining existing or improved physical properties, such as initial modulus, intermediate moduli, tenacity, and shrinkage mentioned above. The outlet and take-up speeds can be 4500-6000 m/min and more.

## CONCLUSION, RAMIFICATIONS, AND SCOPE

Thus, the reader can see that the fiber drawing method and apparatus of this invention can be used to produce industrial fibers at fiber speed  $(V_{fiber})_{max}$  substantially lower than outlet speed  $V_{outlet}$  and take-up speed  $V_{take-up}$  and at substantially lower strain rate  $V_{strain}$ , lower tension in the fiber drawing line, and longer drawing time  $T$  than in the prior art without reducing throughput.

This ~~form~~ provides a basis for achieving some unprecedented results, i.e., producing industrially polymer fibers with improved tensile and other physical properties approaching those obtained in laboratory experiments. This means that the development of a new generation of low-cost, high-performance, aliphatic flexible-chain industrial polymer fibers is feasible. On the one hand, tenacity of the new fibers can be 1/3-1/2 of that of high-cost, high-strength, high-modulus fibers (Kevlar 49®, Twaron®, Spectra®, Dyneema®, et al.) discussed above. On the other hand, the tenacity can be one and a half times and more greater than that of low-cost, low-performance commercial aliphatic flexible-chain polymer fibers. Initial modulus and intermediate moduli can be increased even greater.

Furthermore, this invented method offers additional advantages.

The invented method resolves another fundamental problem of the fiber technology -- how to produce industrial fibers having substantially improved both tensile properties and dimensional stability (low shrinkage) in the high-throughput process without utilizing special heat-setting equipment. This may result in substantial saving in capital expenses, and possibility of a smaller industrial space.

It also provides a more reliable process, which has less breaks, less equipment stops, and less waste, resulting in substantial saving.

While the above description contains many specifics, these should not be considered as limitations on the scope of the invention, but rather as an exemplification of the presented embodiments thereof. Many other variations are possible. For example:

1. The winding and unwinding flyers are located outside the heat chamber, while the heat chamber surrounds the greatest part of the conveyer-drawing members.
2. The invented drawing apparatuses can be arranged in a series or other treating devices may be provided between two drawing apparatuses of the invention; a consecutive arrangement of

two or more invented apparatuses is especially advantageous for achieving the total draw ratios 10 to 1 and higher, like in the case of gel spinning of ultra-high molecular weight polymers, or providing different drawing temperatures at different stages of drawing.

3. A conventional stage of drawing using cylindrical draw rollers may precede or follow the invented apparatus; the rollers ~~may~~ can be used for fine and minute adjustment of the total draw ratio; the draw rollers ~~may~~ can be constructed with or without internal heaters.

4. In the embodiment illustrated in Fig. 1A each spindle is replaced by several consecutive rotating spindles connected by universal joints and arranged either at different or same divergence angles  $\alpha$ .

5. In another embodiment of the invention, each conveyer-drawing member (e.g., the threaded spindle or the chain) consists of three sections. In section I ~~they~~ the conveyer-drawing members are arranged in parallel to the central axis, in section II they diverge from the central axis (as in the embodiments illustrated in Figs. 1A, 2A, and 3A), and in section III they are arranged in parallel to the central axis again. Sections I and III are outside of the heat chamber, their transfer points with section II being arranged right before and right after the heat chamber respectively. Section II is predominantly inside of the heat chamber (at least 85% of its path is inside of the chamber). That prevents the temperature of the conveyer-drawing members in section II from falling substantially below the temperature of the heat chamber when they leave the chamber. The fiber is wound in successive fiber loops about the conveyer-drawing members by the ~~fiber winding~~ fiber-winding device in the beginning of section I, moved along sections I-III, and unwound at the end of section III by the unwinding device. In this arrangement the fiber enters the heat chamber in the form of coiled controlled loops and cools down in the form of coiled controlled loops after the heat chamber. The conveyer-drawing members in section II could be subdivided into two or more sections, which are arranged consecutively at transfer points.

6. In the embodiment of Fig. 1A, the threaded spindles are conical with diameter increased toward the delivery ends. Each point of the fiber loops rotates about the central axis with

increasing linear speed while moving from the receiving to delivery ends. Optimization of this effect can result in better uniformity of the drawn fiber.

7. In the embodiments of Figs. 1A-3A, a stepping electric motor is used to drive the conveyer-drawing members (the threaded spindles, endless chains, etc.), the winding flyer, and the unwinding flyer.

8. In another embodiment of the invention, the conveyer-drawing members are cantilever having either the delivery or receiving ends free, with no support. This is an alternative design to the embodiments of Figs. 1A-3A having some advantages in taking the fiber off the apparatus or feeding the fiber to the apparatus. In the case of the cantilever conveyer-drawing members having free delivery ends, the leading fiber loop can be taken off from the delivery ends by the take-off mechanism without the unwinding flyer.

9. In the embodiment of Fig. 1A, some of the threaded spindles rotate in a direction opposite to the direction of rotation of the other spindles. Oppositely, rotating spindles have opposite threads. For example, the spindles rotating in one direction have right hand thread and the spindles rotating in the opposite direction have left hand thread. Consequently, all spindles transport the fiber thereon in the same direction, but since opposite forces are exerted by oppositely rotating threaded spindles in circumferential direction on the fiber, the coiled fiber loops are not rotated ~~as a whole~~ about the central axis.

10. In the embodiment of Fig. 3A rollers 98 have tracer pins attached to their lateral surfaces instead of gears 100. These pins slide along specially profiled stationary slots, while ~~rolls~~ rollers 98 are moved from the receiving to delivery ends, and turn rollers 98. Therefore, gears 84, 86, and 90 and shaft 88 are not installed.

11. In the embodiments of Figs. 2A and 3A, circulating endless cables, belts, bands, cords, or escalator-type moving stairs can be used as the conveyer-drawing members instead of the chains.

12. In the embodiments of Figs. 2A and 3A, the displacing ~~means~~ members comprise guide plates, rods or pins mounted on the chains, cables, belts, bands, cords, or escalator-type moving stairs instead of the rollers and the guide semi-rings.
13. The fiber draw ratio can be changed, in addition to that presented in the embodiments of Figs. 1A-3A, by changing positions along the central axis where the fiber is received on the conveyer-drawing ~~means~~ members and/or taken off from the conveyer-drawing ~~means~~ members, circumferences of the first fiber loop at the receiving ends and/or the leading fiber loop at the delivery ends being changed respectively.
14. The fiber draw ratio can be changed, in addition to that presented in the embodiments of Figs. 1A-3A, by adjusting the distance between the delivery ends and the central axis, circumference of the leading fiber loop being changed.
15. In the embodiments of Figs. 1A-3A, the fiber can be treated, while being drawn, using hot plates or baths of active media instead of the heat chambers.

Accordingly, the scope of the invention should be determined not by the embodiments illustrated, but by the appended claims and their legal equivalents.

## APPENDIX

### Designations for symbols

$\lambda$	Draw ratio, i.e., the extent of the fiber drawing
$V_{\text{fiber}}$	Linear speed along the fiber axis of fiber points in the process of drawing; in the invented drawing apparatus the speed is different for different fiber points of each fiber section being drawn between two adjacent conveyer-drawing members
$V_{\text{fiber1}}$	Speed $V_{\text{fiber}}$ in the beginning of the fiber drawing
$V_{\text{fiber2}}$	Speed $V_{\text{fiber}}$ at the end of the fiber drawing
$V_{\text{surface1}}$	Linear surface speed of the feed rollers (in the case of <u>conventional</u> drawing by rotating rollers)
$V_{\text{surface2}}$	Linear surface speed of the receiving rollers (in the case of <u>conventional</u> drawing by rotating rollers)
$(V_{\text{fiber}})_{\text{max}}$	The highest value of fiber speed $V_{\text{fiber}}$ in the drawing process
$V_{\text{fiberK}}$ and $V_{\text{fiberP}}$	Speed $V_{\text{fiber}}$ of fiber points K and P (Fig. 5) in the invented drawing apparatus
$V_{\text{inlet}}$	Fiber inlet speed, which is a fiber linear speed along the fiber axis of feeding the fiber to the drawing apparatus
$V_{\text{outlet}}$	Fiber outlet speed, which is a fiber linear speed along the fiber axis of conveying the drawn fiber from the drawing stage either to the next stage of the continuous fiber making process or to the receiving package.
$V_{\text{take-up}}$	Take-up speed, which is a fiber linear speed along the fiber axis of taking-up the drawn fiber on the receiving package
$V_{\text{strain}}$	Strain rate, which is a relative deformation of the fiber (strain) in a unit time
$T$	Time of drawing
$V_{\text{loop}}$	Speed of conveying of the fiber loops along the central axis
$d$	Distance between adjacent loops in the fiber coil along the central axis, i.e., a pitch of the fiber coil

$\Delta t \Delta T$	Time needed for the fiber loop to pass distance $d$
$L$	Circumference of the leading fiber loop at the delivery ends
$L'$	Circumference of the first fiber loop at the receiving ends
$n$	Number of the conveyer-drawing members
$A$	Ratio $V_{\text{outlet}}/V_{\text{loop}}$ ( $V_{\text{take-up}}/V_{\text{loop}}$ where $V_{\text{outlet}} = V_{\text{take-up}}$ )
$B$	Ratio $V_{\text{outlet}}/(V_{\text{fiber}})_{\text{max}}$
$\alpha$	Divergence angle -- angle between the conveyer-drawing members and the central axis of the apparatus
$L_{\text{fiber}}$	Distance, which each point of the fiber loop passes in the process of rotation of the loops <u>loop by the rotating rollers or spindles</u> about the central axis while the loop as a whole passes distance $d$ along the central axis for time $\Delta t \Delta T$
$L_{\text{total}}$	Total distance, which each point of the fiber loop passes in the process of rotation of the loop <u>by the rotating spindles or rollers</u> about the central axis while the loop as a whole passes from the receiving up to delivery ends
$L_{\text{average}}$	Average circumference of the fiber loops in the heat chamber
$L_i$ and $L_{i+1}$	Circumferences of two adjacent fiber loops
$N$	Number of the fiber loops in the heat chamber
$N'$	Number of the fiber loops with the average circumference $L_{\text{average}}$ , which have the total circumference equals to $L_{\text{total}}$ . <u>(it is a reduction in number of the fiber loops passing the heat chamber for time of drawing <math>T</math> as a result of rotation of the loops about the central axis relative to the case with no rotation)</u>
$M$	Length of the fiber coil along the central axis
$V_{\text{rotation}}$	Fiber linear speed of each point of the fiber loop in the case of rotation of the coiled fiber loops <u>by the rotating rollers or spindles</u> about the central axis; <u>it equals the linear surface speed of these rollers or spindles</u>
$D_{\text{spindle}}$	<u>Inner diameter of the thread of the spindle</u>